Rounding semidefinite relaxations of concave functions of quadratic forms

Chenyang Yuan

Based on joint work with Pablo Parrilo

Toyota Research Institute

Friday 26th July, 2024

Introduction

How to find approximations to 3 seemingly unrelated problems:

- Subspace approximation
- Max-Cut
- Permanent of PSD matrices

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- Simple rounding analysis to obtain optimal approximation factors matching lower-bounds

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Bounding expectations of functions of Gaussians gives analysis for rounding algorithms for optimization problems on the sphere

Subspace Approximation

Given $a_1, \ldots, a_m \in \mathbb{R}^n$ and $p \ge 1$. Find (n-d)-dimensional subspace V that minimizes

$$\left(\sum_{i=1}^m \mathsf{dist}(a_i,V)^p\right)^{\frac{1}{p}}$$

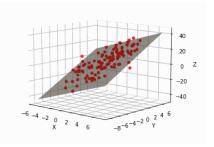
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p = 2 equivalent to least squares, polynomial-time solution via SVD.

 $p=\infty$, minimize maximum distance to V, NP-hard problem in computational convex geometry.



Subspace Approximation SDP Relaxation

$$\min_{V} \left(\sum_{i=1}^{m} \operatorname{dist}(a_{i}, V)^{p} \right)^{\frac{1}{p}} = \min_{X} \left(\sum_{i=1}^{m} (a_{i}^{\top} X X^{\top} a_{i})^{p/2} \right)^{\frac{1}{p}}$$
s.t. $X^{\top} X = I_{d}$

$$X \in \mathbb{R}^{n \times d}$$

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SDP relaxation via convex hull of feasible set (Fantope):

$$\min_{Q} \quad \left(\sum_{k=1}^{m} (a_i^{\top} Q a_i)^{p/2} \right)^{\frac{1}{p}}$$
s.t.
$$\operatorname{Tr}(Q) = d$$

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Constant-factor approximation algorithm [DTV11] for $p \ge 1$, $0 \le d \le n$.

For d = 1 and p > 2, [Gur+16] shows that it is NP-hard to improve constant.

[Gur+16] Guruswami et al. "Bypassing UGC from some optimal geometric inapproximability results". 2016. →御ト→金ト→金ト 重 [DTV11] Deshpande, Tulsiani, and Vishnoi, "Algorithms and hardness for subspace approximation", 2011.

Max Cut

Given $A \succ 0$, the MAXCUT problem is:

$$\max_{x \in \{\pm 1\}^n} \langle x, Ax \rangle$$

 $[\mathsf{BRS15}] \ \mathsf{Briet}, \ \mathsf{Regev}, \ \mathsf{and} \ \mathsf{Saket}. \ \ \mathsf{``Tight} \ \mathsf{hardness} \ \mathsf{of} \ \mathsf{the} \ \mathsf{non-commutative} \ \mathsf{Grothendieck} \ \mathsf{problem''}. \ 2015.$

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Max Cut

Given A > 0, the MAXCUT problem is:

$$\max_{x \in \{\pm 1\}^n} \langle x, Ax \rangle$$

For PSD A, we have a $\frac{2}{\pi}$ -approximation by Nesterov [Nes98].

NP-hard to improve approximation constant. [BRS15]

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Can be improved to 0.878 [GW95] if A is graph Laplacian.



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Max Cut as Optimization on the Sphere

An equivalent formulation over the sphere:

$$\max_{x \in \{\pm 1\}^n} \langle x, Ax \rangle = \max_{\|z\|_2 = 1} \left\| A^{\frac{1}{2}} z \right\|_1^2.$$

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Using variational characterization $\langle x, Ax \rangle = \max_{y \in \mathbb{R}^n} 2 \langle x, y \rangle - \langle y, A^{-1}y \rangle$:

$$\max_{x \in \left\{\pm 1\right\}^n, y \in \mathbb{R}^n} \, 2 \, \langle x, y \rangle - \left\langle y, A^{-1} y \right\rangle = \max_{y \in \mathbb{R}^n} \, 2 \, \|y\|_1 - \left\langle y, A^{-1} y \right\rangle$$

Substitute $y = \lambda A^{\frac{1}{2}}z$, where ||z|| = 1, $\lambda \in \mathbb{R}$.

$$\max_{\|z\|_2 = 1, \lambda \in \mathbb{R}} 2\lambda \left\| A^{\frac{1}{2}} z \right\|_1 - \lambda^2 = \max_{\|z\|_2 = 1} \left\| A^{\frac{1}{2}} z \right\|_1^2.$$

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Generalized to matrix $2 \rightarrow q$ norms when 0 < q <= 2 (MAXCUT equivalent to $2 \rightarrow 1$ norm).

Permanent of a matrix $\operatorname{per}(A) = \sum_{\sigma} \prod_{i=1}^{n} A_{i,\sigma(i)}$

#P-hard to compute in general, NP-hard to compute sign

7/16

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For $A \succeq 0$, $e^{-(1+\gamma)n}$ approximation algorithm [Ana+17; YP21].

NP-hard to approximate better than $e^{-\gamma n}$, current-best approximation factor $e^{-(0.9999+\gamma)n}$ [ENOG24].

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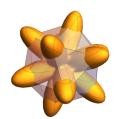
Approximating Permanents of PSD Matrices

Let $A = V^{\dagger}V$ and v_i be the columns of V

We study the following polynomial optimization problem on the complex (n-1)-sphere of radius \sqrt{n} , and its SDP relaxation:

$$\rho(A) \equiv \max_{\|x\|^2 = n} \prod_{i=1}^{n} |\langle x, v_i \rangle|^2$$

$$\operatorname{rel}(A) \equiv \max_{X} \prod_{i=1}^{n} \left\langle X, v_i v_i^{\dagger} \right\rangle \text{ s.t. } \begin{cases} \operatorname{Tr}(X) = n \\ X \succeq 0 \end{cases}$$



Product of Linear Forms and Permanent Approximation

Theorem ([YP21])

Let $\gamma = 0.5772...$ be the Euler-Mascheroni constant. Then

$$e^{-\gamma n} \operatorname{rel}(A) \stackrel{1}{\leq} \rho(A) \leq \operatorname{rel}(A)$$

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Connection to permanent:

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$$e^{-n(1+\gamma)}\operatorname{rel}(A) \stackrel{1}{\leq} e^{-n}\rho(A) \leq \operatorname{per}(A) \stackrel{2}{\leq} \operatorname{rel}(A)$$

Approximating permanent \longleftrightarrow polynomial optimization over sphere

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(1) is tight for low-rank matrices, (2) is tight for high-rank matrices, [ENOG24] found arbitrage to improve approximation by 10^{-4} .

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Given $A_1, \ldots, A_d \succeq 0$. Consider the image of the sphere $\{x \in \mathbb{K}^n \mid ||x|| = 1\}$ under the map

$$A: \mathbb{K}^n \to \mathbb{R}^d_+$$
$$A(x) = (\langle x, A_1 x \rangle, \dots, \langle x, A_d x \rangle)$$

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 $\mathsf{Im}(\mathcal{A})$ is a non-convex set in \mathbb{R}^d , convex hull given by

$$\mathsf{conv}(\mathsf{Im}(\mathcal{A})) = \{(\langle X, A_1 \rangle, \dots, \langle X, A_d \rangle) \mid \mathsf{Tr}(X) = 1, X \succeq 0\}$$

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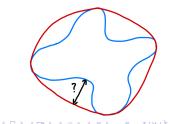
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How well does conv(Im(A)) approximate Im(A)?

What measure of approximation to use?



We study the following relaxation

$$\max_{\|x\|=1} \sum_{i} f(\langle x, A_{i}x \rangle) \quad \overset{\text{relax}}{\longrightarrow} \quad \max_{\mathsf{Tr}(X)=1, \, X \succeq 0} \sum_{i} f(\langle X, A_{i} \rangle),$$

where $A_i \succeq 0$ and f is concave

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$$f(a) = a^p$$
 for $0 \le p \le 1$: Matrix $2 \to \frac{p}{2}$ norm:

- $f(a) = \sqrt{a}$: MAXCUT with PSD objective (ℓ_1 norm)
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- $f(a) = -a \log a$: Entropy maximization of POVM (Reverse KL)



Summary of results

Rounding algorithm: Given optimum $X^* = UU^{\dagger}$, produce unit vector \hat{x} by:

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f(a)	Approximation	Factor $(\mathbb{K}=\mathbb{R})$	Factor $(\mathbb{K}=\mathbb{C})$
a ^p	Multiplicative	$2^p\Gamma\left(1/2+p\right)/\sqrt{\pi}$	$\Gamma(1+p)$
log a	Additive	$\gamma + \log 2$	γ
$-a \log a$	Additive	2	1

Additional gains when we can bound the rank of SDP solution X^*

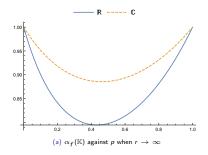


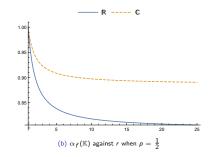
Improved bounds for low-rank solutions

When $f(a) = a^p$ and the solution of X^* has rank r, approximation factor

$$\alpha_f(\mathbb{R}) = \frac{r^p \Gamma(r/2) \Gamma(1/2 + p)}{\Gamma(1/2) \Gamma(r/2 + p)} > \frac{2^p \Gamma(1/2 + p)}{\Gamma(1/2)}$$
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$$\max_{\|x\|=1} \sum_{i} \log(\langle x, A_i x \rangle) \quad \overset{\text{relax}}{\longrightarrow} \quad \max_{\text{Tr}(X)=1, \, X \succeq 0} \sum_{i} \log(\langle X, A_i \rangle),$$

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Key Step: $g(\lambda) = \mathbb{E} \log \sum_{i=1}^{r} \lambda_i |z_i|^2$ is a symmetric concave function

$$\mathbb{E} \log z^{\dagger} U^{\dagger} U z = \mathbb{E} \log \left(\sum_{i=1}^{r} \lambda_{i} |z_{i}|^{2} \right) \leq \mathbb{E} \log \left(\frac{1}{r} \sum_{i=1}^{r} |z_{i}|^{2} \right) = H_{r-1} - \gamma - \log(r)$$

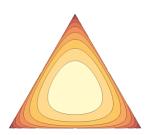
Main Technical Tool/Trick

Bounding function on a domain with symmetry, e.g. simplex

$$\Delta_r = \{\lambda \mid \lambda \ge 0, \sum_i \lambda_i = 1\}$$

Maximum (minimum) of symmetric concave (convex) function on the simplex achieved at center: $\lambda_i = \frac{1}{r}$.

Minumum (maximum) of symmetric concave (convex) function on the simplex achieved at vertices: $\lambda_1 = 1, \lambda_2, \dots, \lambda_r = 0$.



Conclusion

Summary:

Simple technique for obtaining tight bounds on expected values of concave functions of Gaussian variables.

Tight analysis (NP-hard to improve) for Max-Cut, product of linear forms, subspace approximation.

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Questions:

Why do these tight approximation bounds depend on properties of Gaussian variables, though they are not mentioned in the problem description?

Are there other classes of functions of Gaussian random variables for which we can obtain similarly tight approximation bounds?